

Yiddish word of the day

"farlibn zikh"

to fall in love !!

= פִּילְגָּשׁ

Yiddish expression

"Di Kinder in dayne yorn"
zoh beser makhn

= זֶה־זָהָר־בְּסֵבּוּר־זָהָר־
יְמִינָה־בְּסֵבּוּר

"may your children's lives be"
even better

6.3-Matrices of Linear Transf.

Talk teacher Evls

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Canvas (Due 8/24!)

- SETS (What do you think)
 - fill out for me (and enrolled in section) Sam if you

- if > 85% fill out evals everyone gets 5% boost
on final exam.

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Recall: $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ we got the matrix A_T whose columns
are $T(e_i)$

$$\Rightarrow T(\vec{v}) = A_T \vec{v}$$

Now: V, W with bases $\mathcal{B}_V = (v_1, \dots, v_n)$
 $\mathcal{B}_W = (w_1, \dots, w_m)$

$$T: V \rightarrow W \text{ then } T(v) = a_1 w_1 + a_2 w_2 + \dots + a_m w_m$$

$$\text{in particular } T(v_i) = b_1 w_1 + b_2 w_2 + \dots + b_m w_m$$

$$\text{So can form } [T(v_i)]_{\mathcal{B}_W} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} \text{ in } \mathbb{R}^m$$

We define the matrix of T with respect to B_V, B_W as

$$A_{T, B_V, B_W} = \begin{pmatrix} [T(v_1)]_{B_W} & [T(v_2)]_{B_W} & [T(v_n)]_{B_W} \\ \downarrow & \downarrow & \downarrow \\ \text{in } \mathbb{R}^m & \text{in } \mathbb{R}^m & \text{in } \mathbb{R}^m \end{pmatrix}_{m \times n}$$

$$\Rightarrow \text{gives us } [T(v)]_{B_W} = A_{T, B_V, B_W}^{\text{mat}} [v]_{B_V}$$

Ex) $V: \mathbb{R}_2[x]$ $B_V = (1, x, x^2)$

$W: M_{2 \times 2}(\mathbb{R})$ $B_W = \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right)$

$T: V \hookrightarrow W$ as

$$T(a_0 + a_1x + a_2x^2) = \begin{pmatrix} 2a_0 & a_1 - a_2 \\ a_0 & a_1 \end{pmatrix}$$

Find $A_{T, \mathcal{B}_U, \mathcal{B}_W}$

$$\cdot T(1) = \begin{pmatrix} 2 & 0 \\ 1 & 0 \end{pmatrix} \Rightarrow [T(1)]_{\mathcal{B}_W} = \begin{pmatrix} 2 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$
$$= 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 0 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 0 \end{pmatrix} + 0 \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\cdot T(x) = \begin{pmatrix} 0 & 1 \\ 0 & 4 \end{pmatrix} \Rightarrow [T(x)]_{\mathcal{B}_W} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 4 \end{pmatrix}$$

$$\cdot T(x^2) = \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix} \Rightarrow [T(x^2)]_{\mathcal{B}_W} = \begin{pmatrix} 0 \\ -1 \\ 0 \\ 0 \end{pmatrix}$$

$$A_{T, \mathcal{B}_U, \mathcal{B}_W} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & 0 \\ 0 & 4 & 0 \end{pmatrix}_{4 \times 3}$$

Check: Consider the vector $v: 2tx - x^2$ in \mathbb{R}

$$\bullet T(v) = \begin{pmatrix} 2(1) & 1(-1) \\ 2 & 4(1) \end{pmatrix} \Rightarrow [T(v)]_{B_W} = \begin{pmatrix} 4 \\ 2 \\ 2 \\ 4 \end{pmatrix}$$

$$\bullet [v]_{B_V} = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} = 2 \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - 1 \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$$

$$A_{[v]_{B_V}, [T(v)]_{B_W}} [v]_{B_V} = \begin{pmatrix} 4 \\ 0 \\ 2 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \\ 0 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 4 \\ 2 \\ 2 \\ 0 \end{pmatrix} = [T(v)]_{B_W}$$

Again let V, W Vector spaces, B_V, B_W bases.

$T: V \rightarrow W$

$K_U(T)$

nullity(T)

Range(T)

rank(T)

T is injective

T is surjective

T is isomorphism

$A_{T, B_V, B_W} := A$ (m x n matrix)

null(A)

nullity(A)

col(A)

rank(A)

columns of A LI

column space spans \mathbb{R}^m (pivot in every row)

A is invertible (square)

ex) $T: \mathbb{R}[x] \rightarrow M_{2x2}(\mathbb{R})$

"

"

with

$B_V = (1, x, x^2)$

$B_W:$

$\left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right)$

$$T(a_0 + a_1x + a_2x^2) = \begin{pmatrix} 2a_0 & a_1 - a_2 \\ a_0 & ya_1 \end{pmatrix}$$

Find $\text{Ker}(T)$

Use above connection, we'll find

$$\Rightarrow A_T = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & 0 \\ 0 & 4 & 0 \end{pmatrix} \xrightarrow{\text{put into echelon form}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 4 \\ 0 & 0 & 0 \end{pmatrix}$$

Pivot in every column $\Rightarrow \text{null}(A_T)_{B_V, B_W} = \{0\} \Rightarrow \text{Ker } T = \{0\}$

ex2) $V = \mathbb{R}_{\geq 0}[x]$ $B_V = (1, x, x^2, x^3)$

$W = \mathbb{R}_2[x]$ $B_W = (1, x, x^2)$

$D: V \rightarrow W$ derivative $(D(a_0 + a_1 x + a_2 x^2 + a_3 x^3))$
 $= a_1 + 2a_2 x + 3a_3 x^2$

Find A_{D, B_2, B_W} and find $\text{Ker}(D)$

- $$\begin{aligned}
 & D(1) = 0 \Rightarrow [D(1)]_{B_W} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\
 & D(x) = 1 \qquad \qquad \qquad \Rightarrow A_{D(B_W), B_W} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix} \\
 & D(x^2) = 2x \\
 & D(x^3) = 3x^2
 \end{aligned}$$

$$\Rightarrow \text{null}(A_{D,B_1,B_2}) = \text{span} \left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right)$$

$$\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = [v]_{B_0} \Rightarrow v = 1(1) + 0(x) + 0(x^2) + 0(x^3)$$

$$\text{Ker}(D) = \text{Span}(v) = \text{Span}(1) = \text{constants}$$

ex) $V \in M_{2 \times 2}(\mathbb{R})$

$W \in \mathbb{R}^4$

$$B_V = \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right)$$

$$B_W = (e_1, e_2, e_3, e_4)$$

$$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a+b \\ c+d \\ a+c \\ d \end{pmatrix}$$

Find A_T, B_V, B_W

$$\overline{T \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}} = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \Rightarrow \left[\begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right]_{B_W} = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$T \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \left[\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right]_{B_W} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$F \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \left[\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right]_{B^W}$$

$$F \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \left[\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right]_{B^W}$$

$$\Rightarrow A_{T, B_U, B^W} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Q: Is T injective?
If not find

KUT

ex) Change of basis matrix

V vector space with two bases B_1, B_2

$(v_1 \dots v_n)$ $(w_1 \dots w_n)$

Then consider the identity transformation

$$\mathbf{1} : (\mathcal{V}, \mathcal{B}_1) \longrightarrow (\mathcal{V}, \mathcal{B}_2) \quad \mathbf{1}(\mathbf{v}) = \mathbf{v}$$

$$A_{\mathbf{1}, \mathcal{B}_1, \mathcal{B}_2} = \begin{pmatrix} [\mathbf{v}_1]_{\mathcal{B}_2} & [\mathbf{v}_2]_{\mathcal{B}_2} & \cdots & [\mathbf{v}_n]_{\mathcal{B}_2} \\ \downarrow & \downarrow & & \downarrow \end{pmatrix}$$

$$= P_{\mathcal{B}_1 \rightarrow \mathcal{B}_2}$$

$$([\mathbf{v}]_{\mathcal{B}_2} = P_{\mathcal{B}_1 \rightarrow \mathcal{B}_2} [\mathbf{v}]_{\mathcal{B}_1})$$
$$[\mathbf{T}(\mathbf{v})]_{\mathcal{B}_2} = A_{\mathbf{T}, \mathcal{B}_1, \mathcal{B}_2} [\mathbf{v}]_{\mathcal{B}_1}$$

Determinants for Transformations

We want to apply the concept of determinants to

$$T: V \rightarrow V \quad \left(\begin{array}{c} \text{linear operator} \\ \text{D} \end{array} \right)$$

We just showed how to get a matrix $A_{T,B,B}$ from T

Can we define $\det(T) = \det(A_{T,B,B})$?

- A problem is, does this definition depend on choice of basis

If B' is another basis for V , we need to
know the relation between

$$A_{T, B', B'}$$

and $A_{T, B, B}$

turns out

$$\Rightarrow A_{T, B', B'} = P_{B \rightarrow B'} A_{T, B, B} P_{B' \rightarrow B}$$

$$A_{T, B', B'} = (P_{B' \rightarrow B})^{-1} A_{T, B, B} P_{B' \rightarrow B}$$

$$\Rightarrow \det(A_{T, B', B'}) = \det((P_{B' \rightarrow B})^{-1} A_{T, B, B} P_{B' \rightarrow B})$$

$$= \det((P_{B \rightarrow B})^{-1}) \det(A_{T, B, B}) \det(P_{B' \rightarrow B})$$

$$= \det(A_{T, B, B}) \det(P_{B' \rightarrow B}^{-1}) \det(P_{B' \rightarrow B})$$

$$= \det(A_{T, B, B}) \det(P_{B' \rightarrow B}^{-1} P_{B' \rightarrow B})$$

$$= \det(A_{T, B, B})$$

So

$$\det(A_{T, B', B'}) = \det(A_{T, B, B})$$

!

So we define $\det(T) := \det(A_{T, B, B})$

STOP HERE!!

Chapter 2 - Eigenvalues / vectors (For Friday's Class!)

- We saw that we get a diff matrix for $T: V \rightarrow V$ for each basis.
 - Is there a "nice" basis that makes the matrix of T as simple as possible.

ex) For example, is there a basis for V such that the matrix of T with respect to this basis is diagonal.

$$A_{T,B} = \begin{pmatrix} a_1 & & & 0 \\ & a_2 & \cdots & \\ & & \ddots & \\ 0 & & & a_n \end{pmatrix}$$

- If $B = (v_1, \dots, v_n)$ is a basis where the matrix of T is as above

then $T(v_1) = a_1 v_1$, $T(v_2) = a_2 v_2$, ..., $T(v_n) = a_n v_n$

Def: $T: V \rightarrow V$, and $0 \neq v$ a vector in V .

Then if $\underline{T(v)} = \lambda v$ for some λ , we call v an eigenvector and eigenvalue λ

i) A $n \times n$ matrix. A nonzero vector $\vec{v} \in V$ in \mathbb{R}^n is eigenvector of A if $\underline{A\vec{v}} = \lambda \vec{v}$ (this λ is called eigenvalue.)

How to find eigenvectors/values for a given matrix:

Suppose \vec{v} is an eigenvector for A , so $A\vec{v} = \lambda\vec{v}$

$$\Rightarrow A\vec{v} - \lambda\vec{v} = \vec{0}$$
$$(A - \lambda I_n)\vec{v} = \vec{0}$$

\Rightarrow if \vec{v} is in $\text{null}(A - \lambda I_n)$

\Rightarrow this matrix is not invertible.

$$\Rightarrow \det(A - \lambda I_n) = 0 !$$

So we set $\det(A - \lambda I_n) = 0$ and solve for λ

Then we find the $\text{null}(A - \lambda I)$

Ex) $A = \begin{pmatrix} 5 & 4 \\ -2 & -1 \end{pmatrix}$ Find eigenvalues/vectors of A .

1) $A - \lambda I_2 = \begin{pmatrix} 5-\lambda & 4 \\ -2 & -1-\lambda \end{pmatrix}$

2) $\det(A - \lambda I_2) = (5-\lambda)(-1-\lambda) - (4)(-2)$

$$= -5 - 5\lambda + \lambda + \lambda^2 + 8$$

$$= \lambda^2 - 4\lambda + 3$$

3) Solve for lambda:

$$\lambda^2 - 4\lambda + 3 = 0 \Rightarrow (\lambda - 1)(\lambda - 3) = 0$$

$\lambda_1 = 1$: null $\begin{pmatrix} 4 & 4 \\ -2 & -2 \end{pmatrix} \xrightarrow[R_2 \rightarrow R_2 + 2R_1]{R_1/4} \begin{pmatrix} 1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix}$

null space = $\text{Span} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

So $\vec{v}_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ is an eigenvector with eigenvalue 1

Check: $A\vec{v}_1 = \begin{pmatrix} 5 & 4 \\ -2 & -1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} = -1 \begin{pmatrix} 5 \\ -2 \end{pmatrix} + 1 \begin{pmatrix} 4 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

$\lambda_2 = 3$: $\begin{pmatrix} 2 & 4 \\ -2 & -4 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix}$ null space = $\text{span} \begin{pmatrix} -2 \\ 1 \end{pmatrix}$

So $\vec{v}_2 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$ is an eigenvector with eigenvalue 3

Check: $A\vec{v}_2 = \begin{pmatrix} 5 & 4 \\ -2 & -1 \end{pmatrix} \begin{pmatrix} -2 \\ 1 \end{pmatrix} = -2 \begin{pmatrix} 5 \\ -2 \end{pmatrix} + 1 \begin{pmatrix} 4 \\ 1 \end{pmatrix} = \begin{pmatrix} -6 \\ 3 \end{pmatrix} = 3 \begin{pmatrix} -2 \\ 1 \end{pmatrix}$